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Page : 2

where it has a tendency to be slippery, preferably, the non-slip feet 14 are suction cups made of non-marring material although pointed feet, rubber feet, or the like can also be used. The angle and distance device 15 is pivotally mounted to the top surface 26 of the stationary member 12 at the axis of the stationary member 12. Preferably, the angle and distance device 15 is pivotally connected to the stationary member 12 by a snap fastener 28 that allows the angle and distance device 15 to be removed from the stationary member 12. The snap fastener 28 also allows the angle and distance device 15 to rotate 360 degrees relative to the stationary member 12. Therefore, the angle and distance device 15 can be removed from a first stationary member and then attached to a second stationary member. The snap fastener 28 therefore allows the angle and distance device 15 to be used with several different stationary members 12. It is contemplated that a rivet could connect the angle and distance device 15 to the stationary member 12, thereby securely connecting the angle and distance device 15 to the stationary member 12.--

Please insert the following paragraph on page 14, line 18:

--FIG. 17 discloses a method of measuring an area and drawing a template on a work piece using the measuring and layout device 10d of FIGS. 14 and 14A. The method includes the step of providing the measuring and layout device at method step 500, wherein the measuring and layout device 10d includes the stationary member 12d having the flat surface 26d adapted to be marked on and the angle and distance device 15d rotatably coupled to the stationary member 12d. The angle and distance device 15d used in this method includes the longitudinally and laterally rigid extendible tape that can be extended from a central point and the edge that facilitates reliably marking on the stationary member to form an accurate template as the angle and distance device 15d is rotated and the tape is extended and retracted to critical features of an area. The method also includes the step of operably connecting a motor and motor controller 150 to the tape for extending, retracting and axially rotating the tape at step 502, wherein the motor controller is programmed to record data and create an electronic version of the template. The method can also include the step of providing a marker on one end of the tape at step 504, with the motor controller being programmed to move the